

STM32 Quest : 2024 University Developer Contest (GFX & Wireless)

Mission 3 : Graphics + Wireless integration

STMicroelectronics

Mission overview

- Connect the STM32U5G9J-DK2 to STM32WB55RG-NUCLEO via UART
- When receiving data from BLE, send it to U5G9-DK2 over UART then pass it to the GUI task and update the GUI content.
- When pressing a button on the display, send data to WB via UART and WB should transmit the data to the smartphone over BLE.





Behavior graph



Missions' completion conditions

Conditions

- Submit each mission deliverable
 - Mission 1 : zip file with the GUI simulation
 - Mission 2 : video recording the expected behavior between the WB55 and the smartphone.
 - Mission 3 : video recording the expected behavior between the WB55, the U5G9 and the smartphone.
- Note :
 - You are expected to reuse projects created in mission 1 and 2 and add the UART communication between the 2 boards.



Expected result

- Necessary hardware
 - 1x STM32U5G9J-DK2
 - 1x STM32WB55-NUCLEO
 - 3x male-to-female cables (UART RX/TX, GND)
 - 1x USB-C cable to power and flash the STM32U5G9J-DK2
 - 1x USB micro B cable to power and flash the STM32WB55-NUCLEO





UART implementation on U5G9 CubeMX UART configuration



- Enable USART2
- Make sure the parameters settings are the same as on the left picture.
 - Especially, the baud rate must be 115200



UART implementation on U5G9 CubeMX UART configuration

⊘ NVIC Settings				OMA Settings			⊘ GPIO Settings		
	Parameter Settings				😔 User Constants				
Search Sig	gnals								
Search (C	trl+F							Shov	v only
Pin 🗢 🤮	Signal o	Pin Cont	Pin Privil	GPIO o	GPIO m	GPIO P	Maximu	Fast Mo U	Jser L
PA2 L	JSART	n/a	n/a	n/a	Alternat	No pull	Low	n/a	
PA3 L	JSART	n/a	n/a	n/a	Alternat	No pull	Low	n/a	

⊘ NVIC Settings	ings		📀 GPIO Settin	gs
🧭 Parameter Set		😔 ເ	Jser Constants	
NVIC Interr		Enab	Preemption Pri	Sub Prio
USART2 global interrupt		\checkmark	5	0

		GENERATE CODE	
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- Check that the pins used for the USART are PA2 for TX and PA3 for RX
- Enable the interrupt of the USART2 to be able to receive the data from the STM2WB55 on interrupt.
- Then, generate code.



UART implementation on U5G9 CubeMX UART configuration



- Why use USART2 with pin PA2 and PA3 ?
 - Because we want to easily connect the U5G9J-DK2 with the WB55-Nucleo board.
 - For this, using the Arduino connectors is the easiest way.



UART implementation on U5G9 Declare a queue in app_freertos.c

C app_freertos.c × Core > Src > C app_freertos.c > ... 45 /* Private variables -----46 /* USER CODE REGIN Variables */ 47 QueueHandle_t msgQueueUARTtoUI; 48 /* USER CODE END Variables */ C app_freertos.c × Core > Src > C app_freertos.c > @ defaultTask_attributes 99 void MX_FREERTOS_Init(void) { 115

	<pre>void MX_FREERTOS_Init(void) {</pre>
115	
116	/* USER CODE REGIN RIOS QUEUES */
117	<pre>msgQueueUARTtoUI = xQueueCreate(1, sizeof(uint8_t));</pre>
118	/* USEK CODE END KTUS_QUEUES */
119	/* creation of defaultTask */
120	<pre>defaultTaskHandle = osThreadNew(StartDefaultTask, NULL, &defaultTask_att</pre>
121	
122	/* creation of GUI_Task */
123	GUI TaskHandle = osThreadNew(TouchGEX Task NULL &GUI Task attributes):

ributes)

- In order to provide data to the TouchGFX task when running FreeRTOS, we need to create a queue.
 - First, we declare the queue.
 - Second, we initialize it to only store one byte.



UART implementation on U5G9 Receive/Send UART data from main.c

C mai	n.c 9+ X
Core >	Src > C main.c > O MX_GPIO_Init(void)
28 29 30 31 32	<pre>#include "FreeRTOS.h" // need to be included before queue.h #include "queue.h" //For queues in FreeRTOS / OSER CODE END Includes //</pre>
C mai	hc 9+ X
Core >	Src > C main.c >
71	/* USER CODE REGIN PV */
	static char poaranx[2], //Burrer used for receiving data from computer
	extern QueueHandle_t msgQueueUARTtoUI;
75	/* USER CODE END PV */
C main	c 9+ X
Core > S	irc > C main.c > 🛇 MX_DCACHE1_Init(void)
107	int main(void)
140	MX TouchGFX Init():
	/* Call PreOsInit function */
	<pre>MX_TouchGFX_Pre0SInit();</pre>
	/* USER CODE BEGIN 2 */
151 152	HAL_UARI_Receive_II(&huart2, (uint8_t *)pDataRx, 1);
	/* USER CODE END 2 */
	/* USER CODE END 2 */
C main	7° 05ER CODE END 2 °7 c 9+ ×
C main Core ≻	<pre>>* OSER CODE END 2 */ c 9* × Src > C main.c ></pre>
C main Core >	/* USER CODE BEGIN 4 */
C main Core > 781 782 783	<pre>/* USER CODE END 2 */ c 9+ X Src > C main.c > /* USER CODE BEGIN 4 */ Void Send_UART_Message(uint8_t *buf, uint8_t size) /*</pre>
C main Core > 781 782 783 784	<pre>/* USER CODE END 2 */ c 9+ X Src > C main.c > /* USER CODE BEGIN 4 */ Void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); </pre>
C main Core > 781 782 783 784 785	<pre>/* USER CODE END 2 */ c 9+ X Src > C main.c > /* USER CODE BEGIN 4 */ Void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); }</pre>
C main Core > 781 782 783 784 785 786	<pre>/* USER CODE END 2 */ c 9+ X Src > C main.c > /* USER CODE BEGIN 4 */ void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); }</pre>
C main Core > 781 782 783 784 785 786 787 789	<pre>/* USER CODE END 2 */ c 9+ X Src > C main.c > /* USER CODE BEGIN 4 */ void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); } void HAL_UART_RxCpltCallback(UART_HandleTypeDef *huart) </pre>
C main Core > 781 782 783 784 785 786 787 788 788 788	<pre>>* USER CODE END 2 */ c 9+ X Src > C main.c > /* USER CODE BEGIN 4 */ void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); } void HAL_UART_RxCpltCallback(UART_HandleTypeDef *huart) { //(TOD0: checks if the value received is correct or potential </pre>
C main Core > 781 782 783 784 785 786 785 786 787 788 789 790	<pre>/* USER CODE END 2 */ c 9+ X Src > C mainc > /* USER CODE BEGIN 4 */ Void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); } void HAL_UART_RxCpltCallback(UART_HandleTypeDef *huart) { //TOD0: checks if the value received is correct or not xQueueSendFromISR(msgQueueUARTtoUI, &pDataRx[0], 0);</pre>
C main Core > 781 782 783 784 785 786 787 786 787 788 789 790 790 791	<pre>/* USER CODE END 2 */ c 9+ X STC > C mainc > /* USER CODE BEGIN 4 */ Void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); } void HAL_UART_RxCpltCallback(UART_HandleTypeDef *huart) { //TOD0: checks if the value received is correct or not xQueueSendFromISR(msgQueueUARTtoUI, &pDataRx[0], 0); </pre>
C main Core > 781 782 783 784 785 786 787 788 789 790 791 792	<pre>/* USER CODE END 2 */ c 9+ X Src > C mainc > /* USER CODE BEGIN 4 */ void Send_UART_Message(uint8_t *buf, uint8_t size) { HAL_UART_Transmit(&huart2, (uint8_t *)buf, size, 5000); } void HAL_UART_RxCpltCallback(UART_HandleTypeDef *huart) { //TOD0: checks if the value received is correct or not xQueueSendFromISR(msgQueueUARTtoUI, &pDataRx[0], 0); HAL_UART_Receive_IT(&huart2, (uint8_t *)pDataRx, 1); </pre>

- Now that the queue is created, we need to use it when we receive data through UART
 - 1. First, we need to include some FreeRTOS files
 - 2. Then, we declare the queue and a buffer in main.c
 - 3. Enable the interruption trigger in the init() function
 - 4. Create the data reception callback.
- In order to send data to the WB55, we also create a function.

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UART implementation on U5G9 GUI creation to use the UART feature – TouchGFX Designer

• Now, we need to create the GUI and the backend communication. The GUI should resemble the picture below.



Pressing this button will send the current status value to the WB55, in this example it will be 2.

UART implementation on U5G9 GUI creation to use the UART feature - TouchGFX Designer

- You learned how to include a text and an image to a GUI during mission 1.
- Here, you will learn how to create an image based on a Google icon in SVG format. To do this, follow these steps :
 - 1. Create an image widget and in the image selector interface, click on "Stock".
 - 2. Type "lightb" in the search bar
 - 3. Select the image in size 50x50

UART implementation on U5G9 GUI creation to use the UART feature - TouchGFX Designer

SendTextViaUartInteraction		SendTextViaUartInteraction When UARTSendButton clicked	×
Button is clicked			
UARTSendButton			
Call new virtual function			
sendTextViaUart			
Can trigger another interaction			
SendTextViaUartInteraction			

• Create an interaction for the button to send data when pressed.

int8
(0}

 Using the <u>MVP design pattern</u>, after button has been pressed, we send data by propagating the information from View → Presenter → Model → Backend

Image: Constraint of the second s

TouchGF	🗙 > gui > include > gui > model > 🔮 Model.hpp
	class Model
21	protected:
22	ModelListener* modelListener;
	<pre>uint8_t newValue;</pre>
25	};

G Model.cpp ×

```
TouchGFX > gui > src > model > \bigcirc Model.cpp > \bigcirc Model()
           #include "FreeRTOS.h"
           #include "aueue.h"
           extern QueueHandle_t msgQueueUARTtoUI;
           void Send_UART_Message(uint8_t *buf, uint8_t size);
      Model::Model() :
           modelListener(0),
           newValue(0)
 16
      void Model::tick()
           if (uxQueueMessagesWaiting(msgQueueUARTtoUI) > 0)
               xQueueReceive(msgQueueUARTtoUI, &newValue, 0);
               if(modelListener != 0)
                   modelListener->setNewValue(newValue);
```

• This code is used to receive the value available in the queue and send it the View.

G ModelListener.hpp × TouchGFX > gui > include > gui > model > G ModelListener.hpp > ... 6 class ModelListener 17 18 virtual void setNewValue(uint8_t value) {} 19 protected: G MainPresenter.hpp × TouchGFX > gui > include > gui > main_screen > G MainPresenter.l 11 class MainPresenter : public touchgfx::Preser 33 34 35 virtual void setNewValue(uint8_t value); 36

G MainView.hpp ×

TouchGFX	> gui > include > gui > main_screen > 🗘 Main'
7 c]	lass MainView : public MainViewBase
T0	·
17	<pre>void setNewValue(uint8_t value);</pre>

 Once again, we use the <u>MVP design</u> <u>pattern</u>, after receiving data from the queue and we propagate the information in the following manner : Model → ModelListener → Presenter → View

<pre>40 { 41 if(value <= LIGHTBULBS_ON) // verify the number received is correct</pre>
<pre>41 if(value <= LIGHTBULBS_ON) // verify the number received is correct</pre>
42 (
43 lightbulbs_status = value;
44 // Update textArea according to the new value
45 Unicode::snprintf(DataRXTextAreaBuffer, DATARXTEXTAREA_SIZE, "%d", value);
46 DataRXTextArea.invalidate();
47
48 switch(lightbulbs_status)
50 Case LIGHIBULBS_OFF:
51 inground_img.setsimap(courgex::sitimap(sinear)courgetar(courgetar)); inground_img.setsimap(courgetar); isitimap(sinear)courgetar); isitistical and interval
52 IIgn(UDIU2_ING.Set51(map)(CUUCIG1XDIUmap(BITMAP_ICON_INCHE_IMAGES_ACTION_LIGNTBUCE_200_200_/0/0/0_SVG_ID)), hospi.
55 UPERA, 54 Case ITCHTRIURI ON-
55 lightbulb1 Tmg setBitman(touchefx::Bitman(RITMAP ICON THEME IMAGES ACTION LIGHTBULB 200 200 FEC53D SVG TD));
1 iphtbulb2 Imp_setBitmap(touchefx::Bitmap(BITMAP ICON THEME IMAGES ACTION LIGHTBULB 200 200 707070 SVG TD)):
57 break:
58 case LIGHTBULB2 ON:
59 lightbulb1_Img.setBitmap(touchgfx::Bitmap(BITMAP_ICON_THEME_IMAGES_ACTION_LIGHTBULB_200_200_707070_SVG_ID));
60 lightbulb2_Img.setBitmap(touchgfx::Bitmap(BITMAP_ICON_THEME_IMAGES_ACTION_LIGHTBULB_200_200_FFC53D_SVG_ID));
61 break;
62 case LIGHTBULBS_ON:
63 lightbulb1_Img.setBitmap(touchgfx::Bitmap(BITMAP_ICON_THEME_IMAGES_ACTION_LIGHTBULB_200_200_FFC53D_SVG_ID));
64 lightbulb2_Img.setBitmap(touchgfx::Bitmap(BITMAP_ICON_THEME_IMAGES_ACTION_LIGHTBULB_200_200_FFC53D_SVG_ID));
65 break;
66 default:
67 break;
69 lightbulbl_Ing.invalidate();
/0 Iightbulb2_Img.invalidate();

- Here is one way to turn on/off the lightbulbs according to the data received through UART.
 - Don't forget to declare the different lightbulb states in an enum declaration. And initialize the lightbulb_status variable.
 - Note : The application should start with both lightbulbs turned off.

UART implementation on STM32WB55

Adding UART function UART scenario

- If phone sends 1 byte write command to the device, it will be transmitted to the UART TX.
- If UART RX interrupt (1byte) occurs, the received data (1byte) will be transmitted to the phone.

1. Wire setting with U5G9 board

- 1. Open Simple_BLE_Project project by CubeIDE
- 2. Double click "Simple_BLE_Project.ioc" on CubeIDE

- 1. Select LPUART1
- 2. Set Mode to Asynchronous
- 3. Enable LPUART1 global interrupt
- 4. Set Baud rate to 115200

- Save all (Ctrl+Shift+S)
- Code will be updated

Update app_conf.h as follows (location : Simple_BLE_Project/Core/Inc/)

Update stm32wbxx_it.c as follows (location : Simple_BLE_Project/Core/Src/)

life.augmented

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 Update app_ble.c as follows (location : Simple_BLE_Project/STM32_WPAN/App/)

life.augmentec

USER CODE BEGIN APP BLE Init 1
UTIL_SEQ_RegTask(1<<CFG_TASK_BUTTON1_ID, UTIL_SEQ_RFU, task_button1);
UTIL_SEQ_SetTask(1<<CFG_TASK_BUTTON1_ID, CFG_SCH_PRIO_0);</pre>

UTIL_SEQ_RegTask(1<<CFG_TASK_UARTTX_ID, UTIL_SEQ_RFU, task_uarttx); UTIL_SEQ_RegTask(1<<CFG_TASK_UARTTXCALLBACK_ID, UTIL_SEQ_RFU, task_uartrx);</pre>

 Update custom_app.c as follows (location : Simple_BLE_Project/STM32_WPAN/App/)

STM32WB55RGVX FLASH.Id

STM32WB55RGVX_RAM.Id

 Update custom_app.c as follows (location : Simple_BLE_Project/STM32_WPAN/App/)

life.auamented

 Update custom_stm.c as follows (location : Simple_BLE_Project/STM32_WPAN/App/)

Simple_BLE_Project.ioc Simple_BLE_Project Debug.launch STM32WB55RGVX_FLASH.Id

 Update custom_stm.c as follows (location : Simple_BLE_Project/STM32_WPAN/App/)

C STM32WB55RGVX_RAM.Id

life.guamente

 Update custom_stm.h as follows (location : Simple_BLE_Project/STM32_WPAN/App/)

life.augmented

✓ Imple_BLE_Project	/* Includes*/
> 🗱 Binaries	/* USER CODE BEGIN Includes */
> 🗊 Includes	<pre>#include "ble_types.h"</pre>
> 🐸 Core	/* USER CODE END Includes */
> 🤒 Drivers	
Middlewares	
🗸 🐸 STM32_WPAN	/* USER CODE BEGIN EF */
🗸 🗁 App	<pre>void Uart_Rx_Callback(void);</pre>
> app_ble.c	/* USER CODE END EF */
> 🖪 app_ble.h	
> ble_conf.h	
> 🖪 ble_dbg_conf.h	
> custom_app.c	
> 🖻 custom_app.h	
> le custom stm.c	
D custom_stm.h	
In template_server_app.h	
> 🖪 tl_dbg_conf.h	
> 🗁 Target	
> 🐸 Utilities	
> 😂 Debug	
Simple_BLE_Project.ioc	
Simple_BLE_Project Debug.launch	
TM32WB55RGVX_FLASH.Id	
🗟 STM32WB55RGVX_RAM.Id	

Adding UART loopback Step #13

1. Build Project.

- 2. Programming new firmware again.
- 3. Connect your device through BLE
- 4. Enable notify by phone
- 5. Write 0x01.
- 6. Checking the received data.

Expected result

- Necessary hardware
 - 1x STM32U5G9J-DK2
 - 1x STM32WB55-NUCLEO
 - 3x male-to-female cables (UART RX/TX, GND)
 - 1x USB-C cable to power and flash the STM32U5G9J-DK2
 - 1x USB micro B cable to power and flash the STM32WB55-NUCLEO

Useful resources for Graphics

- Demos in TouchGFX Designer
- <u>TouchGFX Technical videos YouTube playlist</u>
- <u>Videos in Korean YouTube playlist</u>
- ST Community
- TouchGFX documentation
- Dribble for UI inspiration
- <u>st.com</u> for information on ST products
- Free image creation tool : <u>Paint.NET</u>

Demos in TouchGFX Designer

TouchGFX – ST Community

Dribble website

Useful resources for Wireless

- STM32WB Wiki page :
 <u>https://wiki.st.com/stm32mcu/wiki/Category:STM32WB_Series</u>
- STM32WB Online training:

<u>https://www.st.com/content/st_com/en/support/learning/stm32-education/stm32-online-training/stm32wb-online-training.html</u>

• STM32WB Online training video session (YouTube)

https://www.youtube.com/playlist?list=PLnMKNibPkDnGkMxFkRArr9uOq_Es_a7vG

Our technology starts with You

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